

Unit 1 Kinematics	Unit 2 Newton's Laws of Motion	Unit 3 Work, Energy, & Power	Unit 4 Systems of Particles & Linear Momentum
<ul style="list-style-type: none"> • Scalar vs. vector • 1-D motion <ul style="list-style-type: none"> ◦ Four kinematic equations ◦ Free-fall motion (gravity is only force) • Cross product and vector addition • $x(t)$, $v(t)$, $a(t)$ graphs <ul style="list-style-type: none"> ◦ Derivatives and integrals • 2-D motion <ul style="list-style-type: none"> ◦ x and y components (like 2 1-D motions) • Special projectile motion formulas (symmetric) <ul style="list-style-type: none"> ◦ $t = (v_x \sin \theta) / g$ to reach max height ◦ $H = (v_x^2 \sin^2 \theta) / 2g$ to reach max height ◦ $R = (v_x^2 \sin 2\theta) / g$ range 	<ul style="list-style-type: none"> • Newton's 1st law: inertia • Newton's 2nd law: $F_{net} = ma$ • Newton's 3rd law: Action and reaction force pair <ul style="list-style-type: none"> ◦ Equal in magnitude, opposite in direction • Free-body diagrams • Equilibrium ($F_{net} = 0$) when at rest OR constant velocity • Friction is fun! $f = \mu N$ <ul style="list-style-type: none"> ◦ Static > kinetic friction • Centripetal = points to center <ul style="list-style-type: none"> ◦ $F_c = (mv^2) / r$ ◦ $ac = v^2 / r$ • Uniform circular motion means speed is constant but direction changes <ul style="list-style-type: none"> ◦ $a = \sqrt{ar^2 + at^2}$ where a_r is towards center and a_t is tangential 	<ul style="list-style-type: none"> • $W = F \Delta r \cos \theta$ and $W = \int_{xi}^{xf} Fx dx$ • Conservative vs. nonconservative forces • Stable vs. unstable equilibrium • $W_{conservative} = -\Delta U$ <ul style="list-style-type: none"> ◦ Gravity = conservative • PE includes both gravitational and elastic • Work-Kinetic Energy Theorem <ul style="list-style-type: none"> ◦ $\Sigma W = \Delta KE$ • Hooke's Law (force law for springs) <ul style="list-style-type: none"> ◦ $F_s = -kx$ • Conservation of energy <ul style="list-style-type: none"> ◦ $E_{mech} = \Delta K + \Delta U$ • Conservation of energy (including work and heat) <ul style="list-style-type: none"> ◦ $\Delta K + \Delta U = W + Q$ • Average power $P = w / \Delta t$ 	<ul style="list-style-type: none"> • Center of mass • Conservation of linear momentum <ul style="list-style-type: none"> ◦ Conserved when $F_{net} = 0$ • Momentum is a vector <ul style="list-style-type: none"> ◦ $\Sigma F = dt/dp$ • Impulse $I = \int_{ti}^{tf} \Sigma F dt$ • Elastic collisions → KE and momentum conserved <ul style="list-style-type: none"> ◦ Objects bounce off each other • Inelastic collisions → KE is NOT conserved, momentum conserved <ul style="list-style-type: none"> ◦ Perfectly inelastic = stick together • Special elastic collision formulas
Unit 5 Rotation	Unit 6 Oscillations	Unit 7 Gravitation	100 FRQ Tips
<ul style="list-style-type: none"> • Same kinematic equations as Unit 1 but with θ, α, ω • Angular and translational <ul style="list-style-type: none"> ◦ $v = r\omega$ tangential speed ◦ $a = r\alpha$ tangential acceleration • Torque $\tau = rF \sin \theta$ is a vector • Net torque $\Sigma \tau = I\alpha$ <ul style="list-style-type: none"> ◦ Clockwise - ◦ Counterclockwise + • Moment of inertia <ul style="list-style-type: none"> ◦ Single particle $I = mr^2$ ◦ Hoop, cylinder, rod, sphere • KE includes both translational and rotational <ul style="list-style-type: none"> ◦ Rotational KE = $(1/2)I\omega^2$ • Angular momentum $L = rmv \sin \theta$ <ul style="list-style-type: none"> ◦ And $L = I\omega$ ◦ Conserved when $\tau_{net} = 0$ • Parallel-axis theorem <ul style="list-style-type: none"> ◦ $I_o = I_{cm} + MD^2$ 	<ul style="list-style-type: none"> • Hooke's Law <ul style="list-style-type: none"> ◦ $F_s =$ restoring force ◦ Negative when F_s and x in opposite directions • Simple Harmonic Motion (sin/cos functions) <ul style="list-style-type: none"> ◦ $x(t) = A \cos(\omega t + \theta_i)$ ◦ $v(t) = -\omega A \sin(\omega t + \theta_i)$ ◦ $a(t) = -\omega^2 A \cos(\omega t + \theta_i)$ • $v_{max} = \omega A$ and $a_{max} = \omega^2 A$ <ul style="list-style-type: none"> ◦ A is max displacement from equilibrium • Energy conservation <ul style="list-style-type: none"> ◦ $(1/2)kA^2 = (1/2)mv^2 = (1/2)kx^2$ 	<ul style="list-style-type: none"> • Orbital speed $v = \sqrt{(GM)/R}$ <ul style="list-style-type: none"> ◦ M is mass of thing being orbited • Gravity $g = GM/R^2$ <ul style="list-style-type: none"> ◦ Add h to R if there is an altitude • Minimum escape velocity $v = \sqrt{2GM/R}$ • Orbital period $T^2 = \frac{4\pi^2}{GM} r^3$ <ul style="list-style-type: none"> ◦ Kepler's 3rd law ◦ Time it takes for a revolution around something • Circular vs. elliptical orbits 	<ul style="list-style-type: none"> • Always list your givens at the start of the problem (m, v, a, F, etc.) • If you are given a graph, use it! • Make sure you know how to integrate and differentiate (i.e. u-sub) • Relationships between variables (i.e. $F_{net} = ma$, and $a = dv/dt$) • Find keywords (constant speed means $a=0$, terminal speed means $t=\infty$) • Visualize, draw a picture or FBD! • Use conservation of energy, especially when heights and movement are involved • Fundamental concepts in units reappear in other units! (FBDs, kinematic equations, etc.)