











<b>Unit 1</b> Kinematics	<b>©Unit 2</b> Dynamics	<b>Unit 3</b> Circular Motion & Gravitation	<b>从Dnit 4</b> Energy
<ul> <li>Vector vs. Scalar: Vectors include directions</li> <li>Displacement vs. Distance</li> <li>Velocity vs. Speed: Velocity is a vector.</li></ul>	<ul> <li>Equilibrium: net force is equal to 0</li> <li>Newton's 1st Law         <ul> <li>Law of Inertia</li> </ul> </li> <li>Newton's 2nd Law         <ul> <li>Force = mass x acceleration</li> </ul> </li> <li>Newton's 3 ← Especially ∑F=ma         <ul> <li>Third Law Force Pairs (equal and opposite)</li> </ul> </li> <li>Friction Ff = F<sub>n</sub>µ         <ul> <li>Coefficient of friction (µ)</li> </ul> </li> <li>Ramps/Inclined Planes         <ul> <li>Know how to create free body diagram with angles</li> </ul> </li> <li>Force Body Diagrams</li> <li>Force and Net Force</li> </ul>	<ul> <li>Centripetal Force: not a force, just an expression for the net force         <ul> <li>Fc = mv²/r</li> </ul> </li> <li>Centripetal Acceleration         <ul> <li>Ac = v²/r</li> </ul> </li> <li>Universal Gravitation</li> <li>Uniform Circular Motion: constant speed (magnitude of velocity is constant)</li> <li>Combos with Forces, Energy, Simple Harmonic Motion, Rotation</li> <li>Inertial mass vs. Gravitational mass         <ul> <li>How do you find each one experimentally?</li> </ul> </li> </ul>	<ul> <li>Work (W = Fd)         <ul> <li>Parallel: (+) Work</li> <li>Antiparallel: (-) Work</li> </ul> </li> <li>Work = Change in Energy</li> <li>PEg, PEs, 2 kinds of KE         <ul> <li>PEg = mgh</li> <li>PEs = (½) kx²</li> <li>KE = (½) mv²</li> <li>KEr = (½) lω² (rotational motion)</li> </ul> </li> <li>Mechanical Energy: the sum of a system's kinetic and potential energy</li> <li>Power (P = W/t) or (P = Fv)</li> <li>Conservation of Energy</li> <li>Bar Charts, Graphs &amp; Diagrams</li> </ul>
Unit 5  Momentum	<b>Unit 6</b> Simple Harmonic Motion	<b>Whit 7</b> Torque & Rotational Motion	🢯 FRQ Tips
<ul> <li>Momentum (p=mv)</li> <li>The direction of momentum is the same as the direction of motion</li> <li>Impulse (J = Ft)</li> <li>F vs t graphs (impulse = area under curve)</li> <li>Conservation of Momentum</li> <li>Center of Mass</li> <li>Combo with Energy, Rotational, Forces</li> <li>Collisions (Inelastic vs. Elastic)         <ul> <li>Elastic → Kinetic Energy and Momentum are conserved</li> <li>Inelastic → Momentum is conserved</li> </ul> </li> <li>The velocity of the center of mass in a closed system is constant</li> </ul>	<ul> <li>Spring &amp; Pendulum</li> <li>Energy relationships</li> <li>F, a, v, x ← Diagrams &amp; Graphs</li> <li>Combo with Forces, UCM, Energy, Rotational</li> <li>Hooke's Law (F = kx)</li> <li>Period Equations</li> <li>What affects the period of a pendulum? <ul> <li>T = 2π(√l/√g)</li> <li>L is the length of a pendulum</li> <li>g is the gravitational field</li> </ul> </li> <li>What affects the period of a mass on a spring?</li> <li>T = 2π(√m/√k)</li> <li>m is the mass attached to the spring</li> <li>k is the spring constant → a higher spring constant is indicative of a stiffer spring</li> </ul>	<ul> <li>Rotational Kinematics (θ,ω,α)         <ul> <li>Same as Unit 1 Big 4 equations, but with new symbols</li> <li>Remember x = θR, v = ωR, a = αR</li> </ul> </li> <li>Torque &amp; Moment of Inertia (Στ = Iα)</li> <li>Torque: a force applied to a point on an object about the axis of rotation (not the center of mass)</li> <li>Net Torque causes angular acceleration</li> <li>Rotational KE and Conservation of Energy</li> <li>Angular Momentum &amp; Conservation of Momentum</li> <li>Angular "Impulse"</li> </ul>	FRQ Breakdown:  Experimental Design: Tests ability to design and analyze lab data.  Quantitative & Qualitative Translation: Tests ability to translate between quantitative and qualitative reasoning.  Paragraph Argument: Tests ability to make a coherent argument in a physics phenomenon.  Short-Answer (2): Tests skills not highlighted in other questions.  Solving Tips:  Does this equation model the correct observations?  Are the variables showing a direct or indirect relationship?  Cite info from the problem  Bring in Basic Physics  Describe how the info works with the Physics  Answer the question with a claim