

AP Physics Study Guide

Further Applications of Newton's Laws - Friction, Drag, and Elasticity

From Simple Studies, <https://simplestudies.edublogs.org> & @simplestudiesinc on Instagram

All images are from the Openstax college physics textbook

Friction is a force that opposes relative motion between systems in contact

- It is parallel to the contact surface between systems and always in a direction that opposes motion or attempted motion of the systems relative to each other
- If two systems are in contact and moving relative to one another, the friction between them is called **kinetic friction**
 - Ex: A hockey puck slowing down on ice
- When objects are stationary, **static friction** can act between them
 - Ex: Pushing a heavy crate that won't move
 - The static friction is usually greater than the kinetic friction between objects

The **magnitude of static friction** is $f_s \leq \mu_s N$

- μ_s is the coefficient of static friction
- N is the magnitude of the normal force
- Once the applied force exceeds $f_{s(max)}$, the object will move
 - $f_{s(max)} = \mu_s N$

The **magnitude of kinetic friction** is $f_k = \mu_k N$

- μ_k is the coefficient of kinetic friction
- N is the magnitude of the applied force

The coefficients of static and kinetic friction depend on the system the objects are acting upon:

Table 5.1 Coefficients of Static and Kinetic Friction

| System | Static friction μ_s | Kinetic friction μ_k |
|-----------------------------------|-------------------------|--------------------------|
| Rubber on dry concrete | 1.0 | 0.7 |
| Rubber on wet concrete | 0.7 | 0.5 |
| Wood on wood | 0.5 | 0.3 |
| Waxed wood on wet snow | 0.14 | 0.1 |
| Metal on wood | 0.5 | 0.3 |
| Steel on steel (dry) | 0.6 | 0.3 |
| Steel on steel (oiled) | 0.05 | 0.03 |
| Teflon on steel | 0.04 | 0.04 |
| Bone lubricated by synovial fluid | 0.016 | 0.015 |
| Shoes on wood | 0.9 | 0.7 |
| Shoes on ice | 0.1 | 0.05 |
| Ice on ice | 0.1 | 0.03 |
| Steel on ice | 0.4 | 0.02 |

The **drag force** is found to be proportional to the square of the speed of the object

- It depends on the shape of the object, its size, its velocity, and the fluid it is in
- $F_D = .5C\rho Av^2$
 - C is the drag coefficient
 - A is the area of the object facing the fluid
 - v is the speed of the object
 - ρ is the density of the fluid
- Using Newton's second law, we can determine that at the terminal velocity $mg = F_D$

○ So, $mg = .5C\rho Av^2$

Table 5.2 Drag Coefficient Values Typical values of drag coefficient C .

| Object | C |
|-----------------------|------|
| Airfoil | 0.05 |
| Toyota Camry | 0.28 |
| Ford Focus | 0.32 |
| Honda Civic | 0.36 |
| Ferrari Testarossa | 0.37 |
| Dodge Ram pickup | 0.43 |
| Sphere | 0.45 |
| Hummer H2 SUV | 0.64 |
| Skydiver (feet first) | 0.70 |
| Bicycle | 0.90 |
| Skydiver (horizontal) | 1.0 |
| Circular flat plate | 1.12 |

Stokes' Law states that $F_s =$

- r is the radius of the object
- η is the viscosity of the fluid
- v is the object's velocity

$$6\pi r\eta v$$

Deformation is a change in shape due to the application of a force

- Even very small forces are known to cause some deformation
- **Hooke's Law** states that $F = k\Delta L$
 - ΔL is the amount of deformation (like change in length) produced by F
 - k is a proportionality constant that depends on the shape and composition of the object and the direction of the force
 - The proportionality constant depends on a number of factors for the material

Stress is the ratio of force to area

- Stress = F/A
- **Strain** is the ratio of the change in length to length
 - Strain = $\Delta L/L_0$

- **Shear deformation** behaves similarly to tension and compression and can be described with similar equations

- $\Delta x = \frac{1F}{SA} L_0$

- S is the shear modulus
- F is the force applied perpendicular to L_0 and parallel to the cross-sectional area A

