



On the way to a future of autonomous driving

Safety



93% of all car accidents are caused by human errors

Efficiency



People spending more than 4 years of life in cars

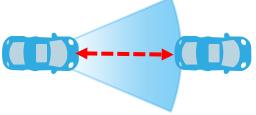
Comfort



People like to text, surf or just enjoy time in cars

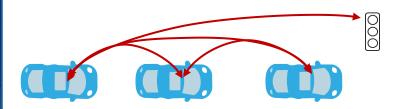
Autonomous and/or cooperative systems

Autonomous Systems e.g. Pre-collision safety system



On-board sensors are used to detect objects (other vehicles, signs, pedestrians) around the vehicle within the visibility range

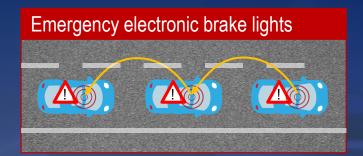
Cooperative Systems e.g. Traffic hazard warning

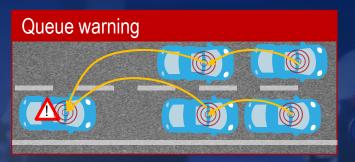


Communication with infrastructure or other vehicles enables detection of objects and 'events' **outside the visibility range**

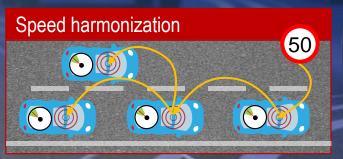
Enhanced safety systems leverage the smart use of both approaches

Typical cooperative safety applications addressed by V2x

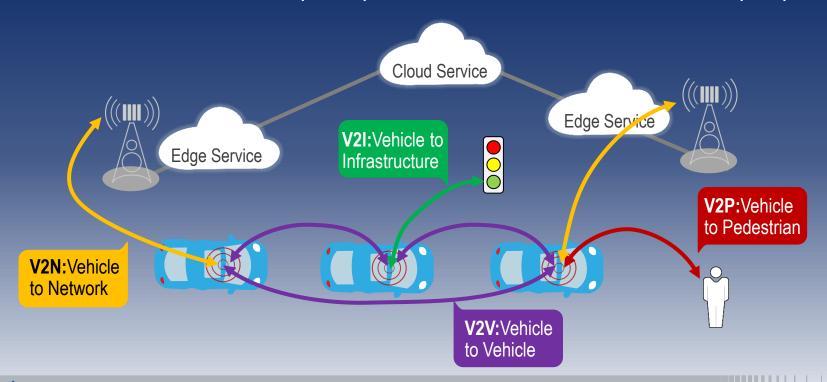








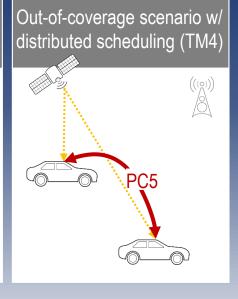
V2X communication architecture: V2V | V2N | V2I | V2P Direct communication (PC5) or network communication (Uu)





3GPP Rel. 14: Adoption of LTE-D2D PC5 in a dedicated carrier for V2V in-coverage and out-of-coverage scenarios

In-coverage scenario w/ eNodeB scheduling (TM3)



Reused channel structure of sidelink communication

Time synchronization via GNSS

New arrangement of resources into resource pools (RPs)

DMRS extension to cope with relative speed of up to 500 km/h

Spectrum sensing and collision avoidance for distributed scheduling

Introduction the concept of zones for transmission resources

Essential to ensure interoperability and required performance: Test and certification of C-V2x communication devices

LTE-V (PC5) Test setup



09.05.2018 | Test & Measurement

Rohde & Schwarz first to provide 3GPP Cellular-V2X device testing through application layer

Supporting end-to-end C-V2X safety related scenarios, the R&S CMW500 wideband radio communication tester enables cellular vehicle-to-everything (C-V2X) device verification in the lab

- LTE-PC5 communication test
 - Transmission Mode 4 (3GPP Rel.14, PSCCH, PSSCH)
 - Out-of-coverage operation with GNSS synchronization
- GCF Protocol Conformance
 - LTE-V2V GCF Work Item 281 (V2V)
 - LTE-V2X GCF Work Item 282 (V2X)

C-V2x signaling solution for 3GPP Rel.14



First C-V2x signaling solution on the market

CMW500 MLAPI based C-V2x Test Cases

The demo shows vehicle-to-vehicle (V2V) PC5 mode communications between a simulated vehicle (DUT) and the R&S®CMW500.

Transferring ITS messages from one vehicle to the other will be demonstrated. E.g. if one vehicle brakes, it will be seen in the other vehicle.

Link: https://www.youtube.com/watch?v=EMam1ve4mCQ



C-V2x enhancement in 3GPP focusing on specific use cases requiring high data rates and lower latency

Vehicle Extended **Platooning** sensors Support of low latency, high data rate links to exchange sensor data intention information trajectory data Remote Advanced driving **Driving**

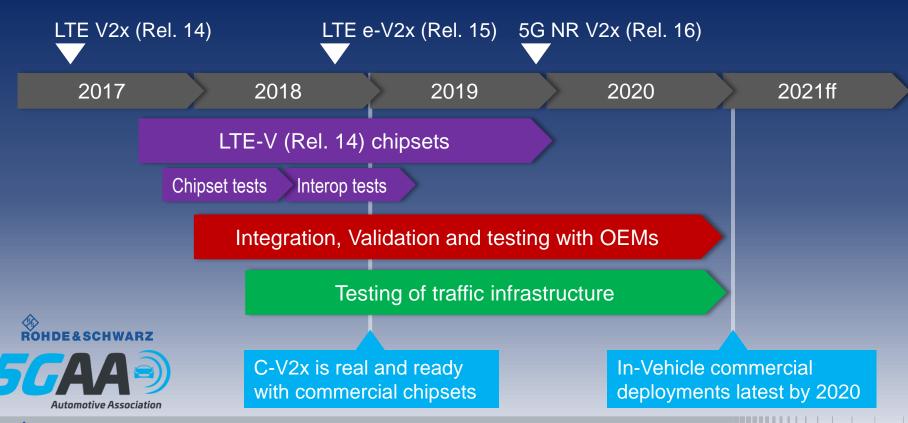
Aggregation of up to 8 PC5 carriers (TM3&TM4)

Support of 64 QAM for higher data rate

Reduce the max. time between L1 packet arrival and resource selected for transmission from 20 to 10 ms

Transmit diversity

5GAA timeline for deployment of LTE-V2x (V2V, V2I)



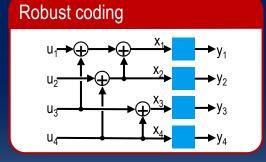
5G started with trying to define a wide range of applications first and define a very flexible 5G NR numerology to support most of them

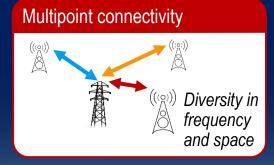




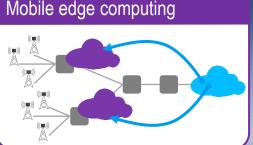
5G NR technology cornerstones to meet reliability and latency requirements of URLLC&V2X applications

Network Virtualization app specific slices





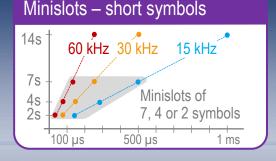




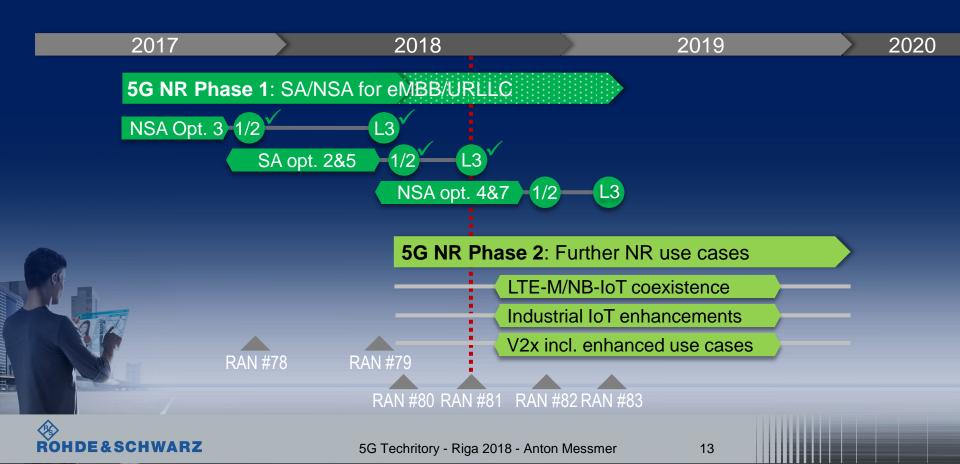


- time →

frequence



3GPP RAN 5G NR standardization overview



We help our customers to realize the vision of automated driving with dedicated test solutions for the automotive market



Signal analysis for highfrequency radar signals



Determine the permissibility of radome material.



Testing of radars with echo generation



Reliable, automated test solutions for V2X



Emergency call - independently certified test solution



Testing invehicle communication networks





